# Stein-like Shrinkage Estimation of Panel Data Models with Common Correlated Effects 

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#### Abstract

This paper examines the asymptotic properties of the Stein-type shrinkage combined (averaging) estimation of panel data models. We introduce a combined estimation when the fixed effects (FE) estimator is inconsistent due to endogeneity arising from the correlated common effects in the regression error and regressors. In this case the FE estimator and the CCEP estimator of Pesaran (2006) are combined. This can be viewed as the panel data model version of the shrinkage to combine the OLS and 2SLS estimators as the CCEP estimator is a 2SLS or control function estimator that controls for the endogeneity arising from the correlated common effects. The asymptotic theory, Monte Carlo simulation, and empirical applications are presented. According to our calculation of the asymptotic risk, the Steinlike shrinkage estimator is more efficient estimation than the CCEP estimator.


Key Words: Endogeneity, Panel data, Fixed effect, Common correlated effects, Shrinkage, Model averaging, Local asymptotics, Hausman test.

JEL Classification: C13, C33, C52

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## 1 Introduction

This paper considers a Stein-like (1956) shirinkage estimation of panel data models. The Stein shrinkage estimators have Bayesian interpretations which leads to a model combination framework parallel to Bayesian model averaging (BMA) of Jeffreys (1961), which is one of the most commonly used model combination method in statistical learning, see Hastie et al (2009, Section 8.8). It can be shown that BMA produces a Stein-type shrinkage estimator. See Judge and Bock (1978, pp. 173-176).

In this important development of shrinkage estimation, Dale Poirier has been one of the leading researchers for more than four decades. Among his numerous contributions in Bayesian analysis in econometrics and statistics, he already developed in early 1980s an idea similar to the concept of model averaging (Hansen 2007). The BMA assigns prior probabilities of the candidate models being the true model, while there is little guidance in the literature on elicitation of prior probabilities. An exception is the model occurrence framework developed in Poirier and Klepper (1981) and Poirier (1988), and applied in Koop and Poirier (1995). The model occurrence is related to model averaging (e.g., Hansen 2007) as its focus is on how the underlying model occurrence probabilities of the competing models depend on characteristics of the environments in which the data subsets are generated. In Poirier and Klepper (1981), classical, Bayesian, and mixed estimation approaches are developed while the Bayesian approaches are shown to be especially attractive whenever the models are nested. Recent literature on BMA includes Draper (1995) and Raftery, Madigan, and Hoeting (1997), and a survey by Hoeting, Madigan, Raftery, and Volinsky (1999).

Although the model averaging has been one of most active topics in recent literature, we have not seen much for panel data models. Recently, there has been increased interest in the estimation of models with error cross-sectional dependence in panel data models. A particular form that has become popular is a common factor error structure with a fixed number of unobserved common factors and individual-specific factor loadings. The most obvious implication of error cross-sectional dependence is that the standard panel data estimators are inefficient and estimated standard errors are biased and inconsistent. One popular approach to this problem is the common correlated effects (CCE) method proposed by Pesaran (2006). The virtue of the CCE estimation is that it can be easily computed by the least squares regression augmented using the cross-sectional averages of the dependent and explanatory variables as proxies for the factors.

In this paper we consider the common correlated effects pooled (CCEP) estimator of Pesaran (2006) in
comparison with the FE estimator. If there exists common correlated effect, the CCEP estimator is consistent and the FE model is inconsistent. On the other hand, if there is no error cross-sectional dependence, both the CCEP and FE estimators are consistent while the FE estimator is efficient. We consider the combined estimator which is a weighted combination of the FE estimator and the CCEP estimator. We study the asymptotic distribution of the combined estimator in a local asymptotic framework where some factor loadings in the error term are in a local neighborhood of zero. We show that under certain conditions, the combined (shrinkage) estimator has strictly smaller risk than the CCEP estimator. The combined estimator also has smaller asymptotic risk compared to the FE estimator unless the endogeneity is very weak. Our simulation result shows that the combined estimator can reduce finite sample MSE relative to the CCEP estimator for all degrees of endogeneity, as well as relative to FE estimator for moderate to large degrees of endogeneity.

Specifically, we consider a panel data regression model of the general form

$$
\begin{equation*}
y_{i t}=x_{i t}^{\prime} \beta+\alpha_{i}+u_{i t}, \tag{1}
\end{equation*}
$$

where $i=1, \ldots, n, t=1, \ldots, T, x_{i t}$ is $q \times 1, z_{i t}$ is $1 \times p, \beta$ is a $q \times 1$ parameter of our interest, $m(\cdot)$ is an unknown smooth function, $\alpha_{i}$ is the individual effect, and $u_{i t}$ is the random error. We are interested in estimation of $\beta$ for the case when the error term $u_{i t}$ is correlated with the regressors $x_{i t}$. The above model suffers from endogeneity which results in the inconsistent estimation of $\beta$.

The solution to the inconsistent estimation depends on what causes the endogeneity: (i) when the individual effect $\alpha_{i}$ is correlated with the regressors $x_{i t}$ or (ii) when the error term $u_{i t}$ is correlated with the regressors $x_{i t}$. In both cases the above model suffers from endogeneity which results in the inconsistent estimation of $\beta$. The first case endogeneity arises when the individual heterogenous effect $\alpha_{i}$ is treated as the random error component and it is correlated with the regressors. We are interested in estimation of $\beta$ for the second case, where the endogeneity arises when regressors that are omitted in the model are correlated with the included regressors $x_{i t}$ such that the regression error $u_{i t}$ and the regressors $x_{i t}$ share common factors (common effects) and thus are correlated. In the first case, the solution is to treat the individual heterogenous effect $\alpha_{i}$ as fixed effects rather than random effects. In the second case, it is to remove the effect of the misspecification, i.e., either by adding them to the model or by controlling for the omitted variables. As the
omitted variables may be unobservable or their data may not be available in hand, we consider the 'control function approach' suggested by Pesaran (2006), which is essentially the 2SLS estimator for the panel data models.

In the mean time however, it is important to note that the solutions to restore the consistency will be based on less efficient estimation. Therefore, there is a trade-off between consistency (bias) and efficiency (variance). In the first case of the endogeneity when the random component $\alpha_{i}$ is correlated with $x_{i t}$, the random effects (RE) estimator is inconsistent but more efficient and the fixed effects (FE) estimator is consistent but less efficient. In the second case when the error term $u_{i t}$ is correlated with $x_{i t}$ due to omitted variables or unobservable variables, the fixed effect estimator (which is an OLS estimator) is inconsistent but relatively more efficient and the common correlated effects (CCE) estimator of Pesaran (2006) (which is a 2SLS estimator) is consistent but less efficient. The CCE estimator can be thought of as a control function estimator as the correlation between $u_{i t}$ and $x_{i t}$ are modelled by a common factor specification in one step and then removed in another step, and therefore it is a 2SLS estimator for the panel data model with the common effects in $u_{i t}$ and $x_{i t}$.

When $u_{i t}$ and $x_{i t}$ are correlated (strong endogeneity), the CCE estimator is preferred to the FE estimator. When $u_{i t}$ and $x_{i t}$ are not correlated (no endogeneity), the FE estimator is preferred to the CCE estimator. Hence, a natural question is which one to choose when the endogenous is weak. The answer is that we combine the FE and CCE estimators when $u_{i t}$ and $x_{i t}$ are weakly correlated. Hence this paper extends Hansen (2017) for panel data models with common correlated effects.

The rest of this paper is organized as follows. To examine and compare the alternative estimators of $\beta$ and their combined estimator, Section 2 gives the models and these estimators. Section 3 presents the asymptotic theory, with all the proofs collected in Appendix (Section 7). Section 4 provides some Monte Carlo simulation results to demonstrate the asymptotic results in finite sample. An empirical application is given in Section 5. Finally, Section 6 concludes.

## 2 Estimating Panel Data Models with Common Correlated Effects

Consider a panel data regression model

$$
\begin{equation*}
y_{i t}=x_{i t}^{\prime} \beta+\alpha_{i}+u_{i t}, \tag{2}
\end{equation*}
$$

where $i=1, \ldots, n, t=1, \ldots, T, x_{i t}$ is a vector of $q$ explanatory variables, $\beta$ is a $q \times 1$ unknown coefficients, $\alpha_{i}$ denotes the individual specific effects and is assumed to be fixed. The disturbance term $u_{i t}$ has a multifactor structure

$$
\begin{equation*}
u_{i t}=\gamma_{i}^{\prime} f_{t}+\varepsilon_{i t} \tag{3}
\end{equation*}
$$

in which $f_{t}$ is an $r \times 1$ vector of individual-invariant time-specific unobserved common effects, $\gamma_{i}$ is an $r \times 1$ stochastic individual-specific factor loading vector, and $\varepsilon_{i t}$ are the idiosyncratic errors assumed to be independent of $x_{i t}$. To model the correlation between the regressors $x_{i t}$ and the errors $u_{i t}$, the regressors may contain the unobserved common factor

$$
\begin{equation*}
x_{i t}=\Gamma_{i}^{\prime} f_{t}+v_{i t}, \tag{4}
\end{equation*}
$$

where $\Gamma_{i}$ is an $r \times q$ stochastic factor loading matrix, and $v_{i t}$ is the $q \times 1$ vector of idiosyncratic components of $x_{i t}$ and is independent of the common effects $f_{t}$.

In vector notation,

$$
\begin{align*}
y_{i} & =X_{i} \beta+\alpha_{i} l_{T}+u_{i},  \tag{5}\\
u_{i} & =F \gamma_{i}+\varepsilon_{i}, \\
X_{i} & =F \Gamma_{i}+v_{i},
\end{align*}
$$

where $y_{i}=\left(y_{i 1}, \ldots, y_{i T}\right)^{\prime}$ is $T \times 1, X_{i}=\left(x_{i 1}^{\prime}, \ldots, x_{i T}^{\prime}\right)^{\prime}$ is $T \times q, u_{i}=\left(u_{i 1}, \ldots, u_{i T}\right)^{\prime}$ is $T \times 1, \iota_{T}$ is the $T \times 1$ vector of ones, $F=\left(f_{1}^{\prime}, \ldots, f_{T}^{\prime}\right)^{\prime}$ is $T \times r, v_{i}=\left(v_{i 1}, \ldots, v_{i T}\right)^{\prime}$ is $T \times q$.

We make the following assumptions on the common factors, their loadings and the individual or unit specific errors.

Assumption 1. $\varepsilon_{i t}$ is independently and identically distributed (iid) across both $i$ and $t$ with $E\left(\varepsilon_{i t}\right)=0$,
$\operatorname{Var}\left(\varepsilon_{i t}\right)=\sigma^{2}>0$ and $E\left\|\varepsilon_{i t}\right\|^{4}<\infty$.
Assumption 2. $v_{i t}$ is distributed independently across both $i$ and $t$ with $E\left(v_{i t}\right)=0, \operatorname{Var}\left(v_{i t}\right)=\Sigma_{i}$ positive definite and $E\left\|v_{i t}\right\|^{4}<\infty$.

Assumption 3. $f_{t}$ is covariance stationary with absolute summable autocovariances, such that $E\left\|f_{t}\right\|^{4}<\infty$.
Assumption 4. $\gamma_{i}$ and $\Gamma_{i}$ are iid across $i$ and independent of $\varepsilon_{i t}$ and $v_{i t}, f_{t}$ for all $i$ and $t$ with fixed means and finite variances. In particular,

$$
\begin{equation*}
\gamma_{i}=\gamma+\eta_{i}, \eta_{i} \sim \operatorname{iid}\left(0, \Omega_{\eta}\right) \tag{6}
\end{equation*}
$$

where $\Omega_{\eta}$ is an $r \times r$ symmetric nonnegative definite matrix, and $\|\gamma\|<K,\|\Gamma\|<K$ and $\left\|\Omega_{\eta}\right\|<K$ for some positive constant $K<\infty$.

Assumption 5. $\varepsilon_{i t}, v_{i t}$ and $f_{t}$ are mutually independent.

First, let $Q_{T} \equiv I_{T}-\iota_{T}\left(\iota_{T}^{\prime} \iota_{T}\right)^{-1} \iota_{T}^{\prime}$, which is a $T \times T$ symmetric idempotent matrix. Further, $Q_{T} \iota_{T}=0$, and so for $i$ th unit, pre-multiplying (5) by $Q_{T}$ gives

$$
\begin{equation*}
Q_{T} y_{i}=Q_{T} X_{i} \beta+Q_{T} u_{i} \tag{7}
\end{equation*}
$$

The $\hat{\beta}_{F E}$ can be expressed as

$$
\begin{equation*}
\hat{\beta}_{F E}=\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} y_{i}\right) \tag{8}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{avar}\left(\hat{\beta}_{F E}\right)=\Psi^{*-1} R^{*} \Psi^{*-1} \tag{9}
\end{equation*}
$$

where $R^{*}=\operatorname{plim}\left(\sigma^{2} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}+\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} F \Omega_{\eta} F^{\prime} Q_{T} X_{i}\right)$, and $\Psi^{*-1}=\operatorname{plim}\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)$. If $\gamma_{i} \neq 0$ so that the error term $u_{i t}$ and $x_{i t}$ have the common correlated effects, the FE estimator is inconsistent. If $\gamma_{i}=0, \hat{\beta}_{F E}$ is consistent and has the following asymptotic distribution

$$
\begin{equation*}
\sqrt{n}\left(\hat{\beta}_{F E}-\beta\right) \xrightarrow{d} N\left(0, \Sigma_{F E}\right), \tag{10}
\end{equation*}
$$

where $\Sigma_{F E}=\sigma^{2}\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}$, under the following additional assumption:

Assumption 6. $\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}$ is bounded and nonsingular.

Next, let us consider the common correlated effects pooled (CCEP) estimator of Pesaran (2006). The
idea underlying the common correlated effects approach is that the unobservable common factors $f_{t}$ can be well approximated by a linear combination of the cross-section averages of the dependent variable and those of the regressors. To illustrate this result, we write (2) and (4) as

$$
\begin{equation*}
z_{i t}=\binom{y_{i t}}{x_{i t}}=B_{i}+C_{i}^{\prime} f_{t}+e_{i t} \tag{11}
\end{equation*}
$$

where

$$
\begin{align*}
e_{i t} & =\binom{\beta^{\prime} v_{i t}+\varepsilon_{i t}}{v_{i t}}  \tag{12}\\
B_{i} & =\binom{\alpha_{i}}{\mathbf{0}}, C_{i}=\left(\begin{array}{ll}
\gamma_{i} & \Gamma_{i}
\end{array}\right)\left(\begin{array}{cc}
1 & 0 \\
\beta & I_{q}
\end{array}\right) \tag{13}
\end{align*}
$$

$z_{i t}$ is $(q+1) \times 1, B_{i}$ is $1 \times(q+1), \mathbf{0}$ is a $q \times 1$ vector of zeros, $C_{i}$ is $r \times(q+1)$, and $I_{q}$ is an identity matrix of order $q$. The covariance matrix of $e_{i t}$ is given by

$$
E\left(e_{i t} e_{i t}^{\prime}\right)=\Sigma_{e, i}=\left[\begin{array}{cc}
\beta^{\prime} \Sigma_{i} \beta+\sigma_{i}^{2} & \beta^{\prime} \Sigma_{i}  \tag{14}\\
\Sigma_{i} \beta & \Sigma_{i}
\end{array}\right]
$$

Then the cross-sectional average is

$$
\begin{equation*}
\bar{z}_{t}=\bar{B}+\bar{C}^{\prime} f_{t}+\bar{e}_{t} \tag{15}
\end{equation*}
$$

where

$$
\begin{equation*}
\bar{z}_{t}=\frac{1}{n} \sum_{i=1}^{n} z_{i t}, \bar{B}=\frac{1}{n} \sum_{i=1}^{n} B_{i}, \bar{C}=\frac{1}{n} \sum_{i=1}^{n} C_{i}, \bar{e}_{t}=\frac{1}{n} \sum_{i=1}^{n} e_{i t} \tag{16}
\end{equation*}
$$

Although not considered here, generally one can consider $\bar{z}_{t}=\bar{z}_{w t}=\sum_{i=1}^{n} w_{i} z_{i t}$, where $w_{i}=\sigma_{i}^{-2} / \sum_{j=1}^{n} \sigma_{j}^{-2}$. If we assume

$$
\begin{equation*}
\operatorname{Rank}(\bar{C})=r \leq q+1, \text { for all } n \tag{17}
\end{equation*}
$$

it follows that

$$
\begin{equation*}
f_{t}=\left(\bar{C} \bar{C}^{\prime}\right)^{-1} \bar{C}\left(\bar{z}_{t}-\bar{B}-\bar{e}_{t}\right) \tag{18}
\end{equation*}
$$

Therefore $f_{t}$ can be approximated by a linear combination of $\left\{\bar{z}_{t} 1\right\}$, if $\bar{e}_{t} \xrightarrow{q . m .} 0$ as $n \rightarrow \infty$ (cf. Lemma 1 in Pesaran 2006). In such a case, we obtain

$$
\begin{equation*}
f_{t}-\left(C C^{\prime}\right)^{-1} C\left(\bar{z}_{t}-\bar{B}\right) \xrightarrow{p} 0 \quad \text { as } n \rightarrow \infty \tag{19}
\end{equation*}
$$

where

$$
\bar{C} \xrightarrow{p} C=\tilde{\Gamma}\left(\begin{array}{cc}
1 & 0  \tag{20}\\
\beta & I_{k}
\end{array}\right) \quad \text { as } n \rightarrow \infty
$$

and $\tilde{\Gamma}=\left(E\left(\gamma_{i}\right) \quad E\left(\Gamma_{i}\right)\right)=(\gamma \Gamma)$.
From (2) and (3), $y_{i t}$ is generated as

$$
\begin{equation*}
y_{i t}=x_{i t}^{\prime} \beta+\alpha_{i}+\gamma_{i}^{\prime} f_{t}+\varepsilon_{i t} . \tag{21}
\end{equation*}
$$

Next, substitute $f_{t}=\left(C C^{\prime}\right)^{-1} C\left(\bar{z}_{t}-\bar{B}\right)$ into (21),

$$
\begin{align*}
y_{i t} & =x_{i t}^{\prime} \beta+\alpha_{i}+\gamma_{i}^{\prime}\left(C C^{\prime}\right)^{-1} C\left(\bar{z}_{t}-\bar{B}\right)+\varepsilon_{i t}  \tag{22}\\
& =x_{i t}^{\prime} \beta+\left(\alpha_{i}-\gamma_{i}^{\prime}\left(C C^{\prime}\right)^{-1} C \bar{B}\right)+\gamma_{i}^{\prime}\left(C C^{\prime}\right)^{-1} C \bar{z}_{t}+\varepsilon_{i t} \\
& =x_{i t}^{\prime} \beta+\bar{h}_{t}^{\prime} c_{i}+\varepsilon_{i t}
\end{align*}
$$

where $c_{i}=\left[\left(\alpha_{i}-\gamma_{i}^{\prime}\left(C C^{\prime}\right)^{-1} C \bar{B}\right) \gamma_{i}^{\prime}\left(C C^{\prime}\right)^{-1} C\right]^{\prime}$ is $(q+2) \times 1$ and $\bar{h}_{t}=\left(\begin{array}{ll}1 & \bar{z}_{t}^{\prime}\end{array}\right)^{\prime}$ is $(q+2) \times 1$. This suggests using $\bar{h}_{t}=\left(\begin{array}{ll}1 & \bar{z}_{t}^{\prime}\end{array}\right)^{\prime}$ as an observable proxy for $f_{t}$. In vector notation,

$$
\begin{equation*}
y_{i}=X_{i} \beta+\bar{H} c_{i}+\epsilon_{i} \tag{23}
\end{equation*}
$$

where $\bar{H}=\left(\iota_{T} \bar{Z}\right)$ is $T \times(q+2), \bar{Z}=\left(\bar{z}_{1}, \ldots, \bar{z}_{T}\right)$ is $T \times(q+1)$. Let $\bar{M}=I_{T}-\bar{H}\left(\bar{H}^{\prime} \bar{H}\right)^{-1} \bar{H}^{\prime}$. Since $\bar{M} \bar{H}=0$,

$$
\begin{equation*}
\bar{M} y_{i}=\bar{M} X_{i} \beta+\bar{M} \epsilon_{i} \tag{24}
\end{equation*}
$$

Now we state the following assumptions:

Assumption 7. $\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} \bar{M} X_{i}$ is bounded and nonsingular.

The CCE estimator can be obtained by performing OLS on the resulting transformed model

$$
\begin{equation*}
\hat{\beta}_{C C E P}=\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} \bar{M} X_{i}\right)^{-1}\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} \bar{M} y_{i}\right) . \tag{25}
\end{equation*}
$$

Following Pesaran (2006), for fixed $T$ and $n \rightarrow \infty$, the asymptotic for CCEP estimator still holds. Under Assumptions 1-5, 7 and with the rank condition (17) satisfied,

$$
\begin{equation*}
\sqrt{n}\left(\hat{\beta}_{C C E P}-\beta\right) \xrightarrow{d} N\left(0, \Sigma_{C C E P}\right), \tag{26}
\end{equation*}
$$

where $\Sigma_{C C E P}=\Psi^{-1} R \Psi^{-1}, \quad R=\operatorname{plim}\left(\sigma^{2} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} M_{f} X_{i}+\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} M_{f} F \Omega_{\eta} F^{\prime} M_{f} X_{i}\right), \Psi^{-1}=$ $\operatorname{plim}\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} M_{f} X_{i}\right), M_{f}=I-F_{1}\left(F_{1}^{\prime} F_{1}\right)^{-1} F_{1}^{\prime}$, and $F_{1}=\left(\iota_{T} \quad F\right)$.

With the common correlated effects, the FE estimator (which is an OLS) does not produce consistent estimates of the coefficients $\beta$ of interest. Pesaran (2006) suggests the CCEP approach that yields consistent estimation in the presence of the correlated unobserved common effects. We now extend Hansen (2017) to propose the following combined estimator of $\beta$, which is a weighted combined FE and CCEP estimator with weights depending on Hausman (1978) statistic:

$$
\begin{equation*}
\hat{\beta}_{c}=w \hat{\beta}_{F E}+(1-w) \hat{\beta}_{C C E P} \tag{27}
\end{equation*}
$$

where

$$
\begin{align*}
w & = \begin{cases}\frac{\tau}{H_{n}} & \text { if } H_{n} \geq \tau \\
1 & \text { if } H_{n}<\tau\end{cases}  \tag{28}\\
H_{n} & =n\left(\hat{\beta}_{C C E P}-\hat{\beta}_{F E}\right)^{\prime}\left[\operatorname{Var}\left(\sqrt{n}\left(\hat{\beta}_{C C E P}-\hat{\beta}_{F E}\right)\right)\right]^{-1}\left(\hat{\beta}_{C C E P}-\hat{\beta}_{F E}\right) \tag{29}
\end{align*}
$$

where $\tau$ is a shrinkage parameter. The degree of shrinkage depends on $\tau / H_{n}$. When $H_{n}<\tau$ then $\hat{\beta}_{c}=\hat{\beta}_{F E}$, When $H_{n} \geq \tau$ then $\hat{\beta}_{c}$ is a weighted average of $\hat{\beta}_{F E}$ and $\hat{\beta}_{C C E P}$, with more weight on $\hat{\beta}_{C C E P}$ when $H_{n}$ is large.

## 3 Asymptotics

The variable $x_{i t}$ is exogenous if $\gamma_{i}=0$. We use the local asymptotic approach. For fixed $T, \gamma_{i}$ is local to zero by setting

$$
\begin{align*}
\gamma_{i} & =\tilde{\gamma}_{i} \rho  \tag{30}\\
\rho & =\frac{1}{\sqrt{n}} \delta \tag{31}
\end{align*}
$$

where $\tilde{\gamma}_{i}$ is an $r \times 1$ constant, and $\rho, \delta$ are scalars. Thus the correlation between $x_{i}$ and $u_{i}$ is local to zero. When $\delta=0, x_{i t}$ are exogenous. When $\delta \neq 0, x_{i t}$ are endogenous. $\delta$ controls the degree of endogeneity. We make a further assumption:

Assumption 8. $X_{i}, i=1, \ldots, n$, are iid over $i . E\left\|x_{i t}\right\|^{2+K}<\infty$ for some $K>0 . E\left\|x_{i t}\right\|^{4}<\infty$.
$V_{1}=\sigma_{\varepsilon}^{2}\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}$ and $V_{2}=\left(\operatorname{plim} \frac{\Psi^{-1} R \Psi^{-1}}{n}\right)^{-1}$, where $\sigma_{\varepsilon}^{2}=E\left(\varepsilon_{i t}^{2}\right)$ is the variance of the idiosyncratic error in (3).

Theorem 1. Under Assumptions 1-8,

$$
\begin{equation*}
\sqrt{n}\binom{\hat{\beta}_{F E}-\beta}{\hat{\beta}_{C C E P}-\beta} \xrightarrow{d} h+\xi, \tag{32}
\end{equation*}
$$

where

$$
\begin{equation*}
h=\binom{\sigma_{\varepsilon}^{-2} V_{1} \Sigma \delta}{0}, \quad \text { with } \Sigma \equiv \operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} F \tilde{\gamma}_{i}, \tag{33}
\end{equation*}
$$

and

$$
\xi \sim N(0, V), \quad \text { with } V=\left(\begin{array}{ll}
V_{1} & V_{21}^{\prime}  \tag{34}\\
V_{21} & V_{2}
\end{array}\right) .
$$

Furthermore,

$$
\begin{equation*}
H_{n} \xrightarrow{d}(h+\xi)^{\prime} B(h+\xi), \tag{35}
\end{equation*}
$$

and

$$
\begin{equation*}
\sqrt{n}\left(\hat{\beta}_{c}-\beta\right) \xrightarrow{d} \tilde{\Psi}=G_{2}^{\prime} \xi-\left(\frac{\tau}{(h+\xi)^{\prime} B(h+\xi)}\right)_{1} G^{\prime}(h+\xi), \tag{36}
\end{equation*}
$$

where $B=G\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-1} G^{\prime}, G_{1}=\left(\begin{array}{ll}I & 0\end{array}\right)^{\prime}, G_{2}=\left(\begin{array}{ll}0\end{array}\right)^{\prime}, G=G_{2}-G_{1}=\left(\begin{array}{ll}-I & I\end{array}\right)^{\prime}$ and $(a)_{1}=\min [1, a]$.

Theorem 1 gives expressions for the joint asymptotic distribution of the FE and CCEP estimator, the Hausman statistic, and the combined estimator as a transformation of the normal random vector $\xi$ and the noncentrality parameter $h$ under the local exogeneity assumption. As noted in Poirier (1995, p. 284) the mean and covariance matrix of the Stein-like combined estimator are complicated. See Judge and Bock (1978, pp. 172-173) for details. In our case, the asymptotic distribution of $\hat{\beta}_{c}$ is written as a random weighted average of the asymptotic distribution of $\hat{\beta}_{F E}$ and $\hat{\beta}_{C C E P}$, as shown in equation (36).

Remark 1. Theorem 1 extends Hansen (2017) for the panel data models and generalizes his results by allowing $V_{1} \neq V_{12}$ and $B=G\left(V_{1}+V_{2}-V_{12}-V_{21}\right)^{-1} G^{\prime}$ to be asymmetric. If $\hat{\beta}_{F E}$ is fully efficient, then $V_{1}=V_{12}=V_{21}$ and $B=G\left(V_{2}-V_{1}\right)^{-1} G^{\prime}$ as in the case of Hansen (2017). In general $\hat{\beta}_{F E}$ may not be fully efficient and so $V_{1} \neq V_{12}$ and $B=G\left(V_{1}+V_{2}-V_{12}-V_{21}\right)^{-1} G^{\prime}$. In that case the derivation of $V_{12}, V_{21}$ is required or they need to be estimated by the use of bootstrap as we do in this paper in Sections 4 and 5.

Next, we compare $\hat{\beta}_{1}, \hat{\beta}_{2}, \hat{\beta}_{c}$ in the asymptotic risk. The asymptotic risk of any sequence of estimators $\beta_{n}$ of $\beta$ can be defined as

$$
\begin{equation*}
R\left(\beta_{n}, \beta, W\right)=\lim _{n \rightarrow \infty} E\left[n\left(\beta_{n}-\beta\right)^{\prime} W\left(\beta_{n}-\beta\right)\right]=R\left(\beta_{n}\right) . \tag{37}
\end{equation*}
$$

Define the largest eigenvalue of the matrix $\frac{A+A^{\prime}}{2}$ and $\frac{A^{*}+A^{* \prime}}{2}$

$$
\begin{align*}
& \lambda_{1}=\lambda_{\max }\left(\frac{A+A^{\prime}}{2}\right),  \tag{38}\\
& \lambda_{1}^{*}=\lambda_{\max }\left(\frac{A^{*}+A^{* \prime}}{2}\right), \tag{39}
\end{align*}
$$

where

$$
\begin{align*}
A & =\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}} W\left(V_{2}-V_{21}\right)\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-\frac{1}{2}},  \tag{40}\\
A^{*} & =\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}} W\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}} . \tag{41}
\end{align*}
$$

Let

$$
\begin{equation*}
d=\frac{\operatorname{tr}\left(W\left(V_{2}-V_{21}\right)\right)}{\lambda_{1}} . \tag{42}
\end{equation*}
$$

Theorem 2. Under Assumptions 1-8, if

$$
\begin{equation*}
d>2, \tag{43}
\end{equation*}
$$

and

$$
\begin{equation*}
0<\tau \leq \frac{2 \lambda_{1}(d-2)}{\lambda_{1}^{*}} \tag{44}
\end{equation*}
$$

then $R\left(\hat{\beta}_{c}\right)=\operatorname{tr}\left[W E\left(\tilde{\Psi} \tilde{\Psi}^{\prime}\right)\right]$,

$$
R\left(\hat{\beta}_{C C E P}\right)=\operatorname{tr}\left(W V_{2}\right),
$$

and

$$
\begin{equation*}
R\left(\hat{\beta}_{c}\right)<R\left(\hat{\beta}_{C C E P}\right)-\frac{\tau\left(2 \lambda_{1}(d-2)-\lambda_{1}^{*} \tau\right)}{\sigma^{-4} \delta \Sigma^{\prime} V_{1}\left[V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right]^{-1} V_{1} \Sigma \delta+q} . \tag{45}
\end{equation*}
$$

Equation (45) shows that the asymptotic risk of the combined estimator is strictly less than that of the CCEP estimator, so long as $\tau$ satisfies the condition (44). $\tau$ appears in the risk bound (45) as a quadratic expression, so there is an optimal choice $\tau^{*}=\frac{\lambda_{1}(d-2)}{\lambda_{1}^{*}}$ which minimizes this bound. The assumption $d>2$
is the critical condition needed in order for the right-hand-side of $(44)$ to be positive, which is necessary for the existence of $\tau$ satisfying (44).

Poirier (1995, p. 284) noted the fact that the asymptotic risk of the combined estimator is strictly less than that of the CCEP estimator, $R\left(\hat{\beta}_{c}\right)<R\left(\hat{\beta}_{C C E P}\right)$, does not imply that $\operatorname{MSE}\left(\hat{\beta}_{c}\right)<\operatorname{MSE}\left(\hat{\beta}_{C C E P}\right)$ for each element of the estimator of the $q \times 1$ coefficients of $\beta$. Poirier (1995) also wrote, "While it may appear that [the James-Stein estimator] is some sort of mathematical trick pulled out of the air, this is not the case. [It] can in fact be given a Bayesian interpretation."

Corollary 1. $R\left(\hat{\beta}_{c}\right)-R\left(\hat{\beta}_{C C E P}\right)<0$, for $d>2$ and $0<\tau \leq \frac{2 \lambda_{1}(d-2)}{\lambda_{1}^{*}}$. In the case $W=\left(V_{2}-V_{21}\right)^{-1}$, $0<\tau \leq 2\left(\frac{q-2}{\lambda_{1}^{*}}\right)$ and $q>2$ which is Stein's (1956) classic condition for shrinkage.

See Poirier (1995, p. 283) for more discussion on Stein's (1956) classic condition for shrinkage. The following two corollaries are obtained with $W=\left(V_{2}-V_{1}\right)^{-1}$.

Corollary 2. $R\left(\hat{\beta}_{F E}\right)=\operatorname{tr}\left(W V_{1}\right)+\sigma^{-4} \delta^{\prime} \Sigma^{\prime} V_{1} W V_{1} \Sigma \delta ; R\left(\hat{\beta}_{F E}\right) \leq R\left(\hat{\beta}_{C C E P}\right)$ when $\sigma^{-4} \delta^{\prime} \Sigma^{\prime} V_{1} W V_{1} \Sigma \delta \leq$ $q$, and $R\left(\hat{\beta}_{F E}\right)>R\left(\hat{\beta}_{C C E P}\right)$ otherwise.

Corollary 3. $R\left(\hat{\beta}_{c}\right)-R\left(\hat{\beta}_{F E}\right)<0$, for $q<\sigma^{-4} \delta^{\prime} \Sigma^{\prime} V_{1} W V_{1} \Sigma \delta, d>2$, and $0<\tau \leq \frac{2 \lambda_{1}(d-2)}{\lambda_{1}^{*}}$.

Corollary 2 indicates that when endogeneity is weak ( $\gamma_{i}$ and hence $\delta_{i}$ is close to zero) the FE estimator may perform better than the CCEP estimator. Corollary 3 indicates that when endogeneity is strong, $d>2$, $0<\tau \leq \frac{2 \lambda_{1}(d-2)}{\lambda_{1}^{*}}$, the combined estimator performs best among these three estimators.

## 4 Monte Carlo

We now investigate the finite sample MSE of our combined estimator in the following simulation design,

$$
\begin{align*}
y_{i t} & =\alpha_{i}+\beta^{\prime} x_{i t}+\gamma_{i}^{\prime} f_{t}+\varepsilon_{i t}  \tag{46}\\
x_{i t} & =\Gamma_{i}^{\prime} f_{t}+v_{i t} \tag{47}
\end{align*}
$$

where $\alpha_{i}$ is drawn from $N(0,1), \varepsilon_{i t} \sim \operatorname{iid} N(0,1), v_{i t} \sim \operatorname{iid} N(0,1)$. The factor is drawn from $N\left(0, I_{r}\right)$. We vary $n \in\{50,100\}, T \in\{8,16\}, q \in\{1,2,3\}, r \in\{1,3\}$ and $\beta \in\{0,1\}$. The parameters of the unobserved common effects in the $x_{i t}$ equation are generated independently across replications as $\Gamma_{i}=$
$\left(\Gamma_{i 1} \Gamma_{i 2} \Gamma_{i 3}\right)$ with $\Gamma_{i 1} \sim \operatorname{iid} N(0.5,0.5), \Gamma_{i 2} \sim \operatorname{iid} N(0,0.5)$, and $\Gamma_{i 3} \sim \operatorname{iid} N(0,0.5)$. Let $\gamma_{i}=\tilde{\gamma}_{i} \rho$ where $\tilde{\gamma}_{i 1} \sim \operatorname{iid} N(1,0.1), \tilde{\gamma}_{i 2} \sim \operatorname{iid} N(1,0.1), \tilde{\gamma}_{i 3} \sim \operatorname{iid} N(1,0.1)$. We consider $\rho$ on a 40-point grid on $[0,0.975] . \rho$ controls the degree of endogeneity.

We generated 5,000 samples on each calculated $\hat{\beta}_{C C E P}, \hat{\beta}_{F E}, \hat{\beta}_{c}$, for the latter we set $\tau=1 / 4$ for $q=1$, $\tau=1$ for $q=2$, and $\tau=\tau^{*}$ otherwise. We also calculated the Hausman pre-test estimator

$$
\hat{\beta}_{P T}=\hat{\beta}_{F E} 1\left(H_{n}<c\right)+\hat{\beta}_{C C E P} 1\left(H_{n} \geq c\right)
$$

where $c$ is the $5 \%$ critical value from the $\chi_{q}^{2}$ distribution. We compare the estimator by relative MSE

$$
\begin{equation*}
\operatorname{MSE}(\hat{\beta})=E(\hat{\beta}-\beta)^{\prime}(\hat{\beta}-\beta) \tag{48}
\end{equation*}
$$

which we normalize by MSE of the CCEP estimator. Thus value less than one indicates improved precision relative to CCEP estimator, and values greater than one indicate worse performance than the CCEP estimator.

We do a bootstrap pairs procedure that resample with replacement over $i$ and uses all observed time periods for a given individual. For data $\left\{\left(y_{i}, X_{i}\right), i=1, \ldots, n\right\}$ this yields $B$ pseduo-samples and for each pseudo-sample we perform regression, yielding $B$ estimates, $b=1, \ldots, B$. The panel bootstrap estimate of the variance matrix is then given by

$$
\begin{equation*}
\hat{V}_{B o o t}\left(\hat{\beta}_{C C E P}-\hat{\beta}_{F E}\right)=\frac{1}{B-1} \sum_{b=1}^{B}\left(\hat{\theta}_{b}-\overline{\hat{\theta}}\right)\left(\hat{\theta}_{b}-\overline{\hat{\theta}}\right)^{\prime} . \tag{49}
\end{equation*}
$$

$b$ denotes the $b$ th of $B$ bootstrap replications, and $\hat{\theta}=\hat{\beta}_{C C E P}-\hat{\beta}_{F E}, \hat{\theta}=B^{-1} \sum_{b} \hat{\theta}_{b}$.
The dotted line (black) is the normalized MSE of the CCEP estimator, the solid line (green) is the normalized MSE of the combined estimator, the longer dashed line (red) is the normalized MSE of the FE estimator, the shorter dashed line (blue) is the normalized MSE of the pre-test estimator.

Figure $3,4,7$ and 8 plots the relative MSE of $\hat{\beta}_{C C E P}, \hat{\beta}_{F E}, \hat{\beta}_{c}, \hat{\beta}_{P T}$ with $q=\{1,2\}$. These are the cases where the equations (43) and (44) are not satisfied, which are sufficient conditions for Theorem 2 to hold, $R\left(\hat{\beta}_{c}\right)<R\left(\hat{\beta}_{C C E P}\right)$. Because these conditions are just sufficient but not necessary, the theorem may or may not hold for these smaller values of $q=1,2$. Indeed, $q=1$ makes the results quite erratic, showing that Theorem 2 does not hold for $q=1$, and somewhat less degree for $q=2$.

In each Figure, subfigure (a) plots the relative MSE for $n=50$; subfigure (b) plot the relative MSE for $n=100$. Figure 1, 2, 3 and 4 plot the relative MSE for $t=8$; Figure 5, 6, 7 and 8 plot the relative MSE for $t=16$. We see that the region of dominance for the combined estimator over the FE and CCEP estimators is greater for smaller $n$ and smaller $t$.

Next consider the case of three endogenous regressors, $q=3$. This is the case where Theorem 2 shows that the weighted asymptotic MSE of the combined estimator is uniformly smaller than that of the CCEP estimator. From Figure 1, 2, 5 and 6 , we see that the MSE of the combined estimator is uniformly smaller than that of the CCEP estimator for all factor loading values. For small $\rho$, the FE estimator has lower MSE than the combined estimator, but the ranking is reversed for moderate values of $\rho$. The FE estimator is very sensitive, which has quite low MSE for very small $\rho$, but very large MSE for large $\rho$. The combined and the pre-test estimators have much smaller MSE than CCEP for small values of $\rho$, but the ranking is reversed for large values of $\rho$. The MSE of the pre-test estimator is generally similar to the FE estimator for small $\rho$. For intermediate values of $\rho$, the MSE of the pre-test estimator is typically larger than the combined estimator. Following Pesaran (2006), $\gamma_{i}$ and $\Gamma_{i}$ are randomly generated as described earlier, while we have also tried with constant $\gamma_{i}$ and $\Gamma_{i}$ which give slightly better but essentially the same results (not reported).

Figure 2 and 6 are the cases, $r=3$. The general nature of the plot is the same, except that the gains is not as strong as in the case $r=1$. We see that the gains from the combined estimator are strong for small $\rho$, with the MSE converging to that of CCEP as $\rho$ increases towards 1. This is consistent with Theorem 2, which shows that the improvement are asymptotically local to $\rho=0$. The FE estimator has lower MSE than the combined estimator, but the MSE of the FE estimator increases dramatically after intermediate values of $\rho$. Still the combined estimator has uniformly smaller MSE than CCEP. In summary, the simulation results provide strong finite sample confirmation of Theorem 2 and its corollaries 1, 2, 3 .

Remark 1. It is interesting that the relative performance of using CCEP versus IFE depends on the true value of $\beta$ is zero or not. We have experimented in simulation with $\beta \in\{0,1\}$. A few figures to compare the results for $\beta \in\{0,1\}$ are reported in figure 9 and 10 . The figures with $\beta=1$ were almost exactly the same as those with $\beta=0$.

Remark 2. We have also tried $2 \tau^{*}$ as this choice still satisfies the classic James-Stein condition in equation (44). could make the MSE of the combined estimator somewhat closer to the MSE of FE when the degree
of endogeneity is small. The results are reported in figure 11 and 12.

## 5 Application

Holly, Pesaran, and Yamagata (2010), hereafter HPY, provide an empirical analysis of changes in real house prices in U.S. using state level data. They use a panel of 49 states over the period 1975-2003 to show that state level real housing prices are driven by economic fundamentals, such as real per capita disposable income, as well as by common shocks, such as changes in interest rates, oil prices and technological change. Baltagi and Li (2014) replicate their results using a panel of 381 metropolitan statistical areas observed over the period 1975-2011. Their replication shows that HPY results are fairly robust. Our empirical analysis relies upon a panel of 49 states over the period 1975-2011 to examine the performance of the combined estimator. Consider the following panel data model for US states

$$
\begin{equation*}
p_{i, t}=\beta_{0}+\beta_{1} y_{i, t}+\beta_{2} g_{i, t-1}+\beta_{3} c_{i, t-1}+\alpha_{i}+u_{i t} \tag{50}
\end{equation*}
$$

where $i=1, \ldots, 49, t=1, \ldots, 17, p_{i, t}$ is the logarithm of the real price of housing in the $i$ th State during year $t$, and $y_{i, t}$ is the logarithm of the real per capita personal disposable income. The net cost of borrowing defined by $c_{i, t-1}=r_{i t}-\Delta p_{i t}$, where $r_{i t}$ represents the long-term real interest rate and $g_{i, t}$ represents the population growth rate. The state-specific effects can be treated as the endowment of climate, location and culture. A more detailed description can be found in HPY. We would expect a rise in $c_{i, t}$ to be associated with a fall in the price income ratio, and hence a negative coefficient for $c_{i, t-1}$. The effect of population growth on real house prices is expected to be positive.

Table 1 suggests that the income elasticity of real house prices for the combined estimator is 1.2151 , and the estimate of the coefficients on the rate of change of population, and the net cost of borrowing are 1.6120 and -0.2047 , respectively for the combined estimator. We find a significant positive effect for population growth and a significant negative effect associated with net cost of borrowing, which are in agreement with the results of HPY. The other two rows report the FE and CCEP estimates. The estimates of the combined estimator lies quite close to that of the CCEP estimator. We bootstrap the data 5000 times by resampling across individuals and keep the time series structure for each individual unchanged. The bootstrap MSE and the standard errors for the above estimates, then, can be calculated based on the estimates of the coefficients
for each bootstrap data. The MSE for FE, CCEP and combined estimators are 3.4250, 2.4288 and 2.1425, respectively. Among these three estimators, the combined estimator has the smallest MSE. The Hausman statistic is 24.9018 . Thus, the exogeneity assumption is rejected at the one percent level of significance, which also indicates that the CCEP estimator is more reliable.

## 6 Conclusions

This paper extends Hansen (2017) for the combined (model averaging) estimation of the parametric panel data model with weak endogeneity (i.e., local to exogeneity) from common correlated effects. We introduce a combined estimation of the FE and CCEP estimators for the panel data models when the FE estimator suffers from inconsistency due to endogeneity arising from the correlated common effects. This can be viewed as the panel data model version of the shrinkage estimator combining the 2SLS estimator (CCEP) and the OLS estimator (FE) because the CCEP estimator is a control function estimator to remove the endogeneity from the correlated common effects.

The use of the combined estimation allows applied researchers to implement efficient estimation under the presence of weak endogeneity. The combined estimation would work even when there is no endogeneity or when there is strong endogeneity, without having to select a consistent estimator or an efficient estimator since the weights in the combined estimator will then be 1 or 0 . Hence, the combined estimator is an omnibus estimator across all degrees of endogeneity, particularly useful when it is not clear which estimator to choose when endogeneity is weak.

## 7 Appendix

Proof of Theorem 1. Here we derive only the asymptotic distribution of the FE estimator for the parametric panel data model with common correlated effects as specified in (3) and (4). The asymptotic distribution of the CCEP estimator for this model is shown in Pesaran (2006). For the joint asymptotic distribution of the FE and the CCEP estimators, the asymptoric covariance $V_{12}$ is complicated and thus we will use bootstrap to estimate $V_{12}$.

To derive the asymptotic distribution of the fixed effects (FE) estimator, we use the notation $h_{1}=G_{1} h$
and $\xi_{1}=G_{1} \xi$ with $G_{1}=\left(\begin{array}{ll}I & 0\end{array}\right)^{\prime}$. Now, write the FE estimator as

$$
\begin{aligned}
\hat{\beta}_{F E} & =\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} y_{i}\right) \\
\hat{\beta}_{F E}-\beta & =\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} u_{i}\right)
\end{aligned}
$$

Given that $u_{i}=F \gamma_{i}+\varepsilon_{i}$,

$$
\hat{\beta}_{F E}-\beta=\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\sum_{i=1}^{n}\left(X_{i}^{\prime} Q_{T} F \gamma_{i}+X_{i}^{\prime} Q_{T} \varepsilon_{i}\right)\right)
$$

Since $\gamma_{i}=\frac{1}{\sqrt{n}} \tilde{\gamma}_{i} \delta$, we have

$$
\begin{aligned}
\hat{\beta}_{F E}-\beta & =\left(\sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\sum_{i=1}^{n}\left(X_{i}^{\prime} Q_{T} F \frac{\tilde{\gamma}_{i} \delta}{\sqrt{n}}+X_{i}^{\prime} Q_{T} \varepsilon_{i}\right)\right) \\
\sqrt{n}\left(\hat{\beta}_{F E}-\beta\right) & =\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} F \tilde{\gamma}_{i} \delta\right)+\left(\frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\frac{1}{\sqrt{n}} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} \varepsilon_{i}\right) \xrightarrow{d} h_{1}+\xi_{1},
\end{aligned}
$$

where

$$
h_{1}=\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} F \tilde{\gamma}_{i} \delta\right)=\sigma_{\varepsilon}^{-2} V_{1} \Sigma \delta,
$$

with $\Sigma \equiv \operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} F \tilde{\gamma}_{i}$, and

$$
\xi_{1} \sim\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1} Z
$$

with

$$
Z=\frac{1}{\sqrt{n}} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} \varepsilon_{i} \sim N\left(0, \sigma_{\varepsilon}^{2}\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)\right)
$$

Hence,

$$
\xi_{1} \sim N\left(0, \sigma_{\varepsilon}^{2}\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}\right)=N\left(0, V_{1}\right)
$$

and

$$
\sqrt{n}\left(\hat{\beta}_{F E}-\beta\right) \xrightarrow{d} N\left(h_{1}, V_{1}\right),
$$

where

$$
V_{1}=\sigma_{\varepsilon}^{2}\left(\operatorname{plim} \frac{1}{n} \sum_{i=1}^{n} X_{i}^{\prime} Q_{T} X_{i}\right)^{-1}
$$

as defined in Assumption 8 with $\sigma_{\varepsilon}^{2}=E\left(\varepsilon_{i t}^{2}\right)$ is the variance of the idiosyncratic error in (3).

Proof of Theorem 2:
Noting that $\sqrt{n}\left(\hat{\beta}_{C C E P}-\beta\right) \rightarrow_{d} G_{2}^{\prime} \xi \sim N\left(0, V_{2}\right)$, then

$$
R\left(\hat{\beta}_{C C E P}\right)=E\left(\xi^{\prime} G_{2}^{\prime} W G_{2}^{\prime} \xi\right)=\operatorname{tr}\left(W V_{2}\right)
$$

Define $\Psi^{*}$ as a random variable without positive part trimming

$$
\Psi^{*}=G_{2}^{\prime} \xi-\left(\frac{\tau}{(h+\xi)^{\prime} B(h+\xi)}\right) G^{\prime}(h+\xi)
$$

Then using the fact that the pointwise quadric risk of $\Psi$ is strictly smaller than that of $\Psi^{*}$

$$
R\left(\hat{\beta}_{c}\right)=E\left(\Psi^{\prime} W \Psi\right)<E\left(\Psi^{* \prime} W \Psi^{*}\right)
$$

we can calculate that

$$
E\left(\Psi^{* \prime} W \Psi^{*}\right)=R\left(\hat{\beta}_{C C E P}\right)+\tau^{2} E\left(\frac{(h+\xi)^{\prime} G W G^{\prime}(h+\xi)}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}}\right)-2 \tau E\left(\frac{(h+\xi)^{\prime} G W G_{2}^{\prime} \xi}{(h+\xi)^{\prime} B(h+\xi)}\right)
$$

By Stein's Lemma: If $Z \sim N(0, V)$ is $q \times 1, K$ is $q \times q$, and $\eta(x): R^{q} \rightarrow R^{q}$ is absolutely continuous, then

$$
E\left(\eta(Z+h)^{\prime} K Z\right)=E \operatorname{tr}\left(\frac{\partial}{\partial x} \eta(Z+h)^{\prime} K V\right)
$$

$\eta(x)=x /\left(x^{\prime} B x\right)$, and

$$
\frac{\partial}{\partial x} \eta(x)=\frac{1}{x^{\prime} B x} I-\frac{2}{\left(x^{\prime} B x\right)^{2}} B x x^{\prime}
$$

Therefore

$$
\begin{aligned}
E\left(\frac{(h+\xi)^{\prime} G W G_{2}^{\prime} \xi}{(h+\xi)^{\prime} B(h+\xi)}\right) & =E \operatorname{tr}\left(\frac{G W G_{2}^{\prime} V}{(h+\xi)^{\prime} B(h+\xi)}-\frac{2 G W G_{2}^{\prime} V}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}} B(h+\xi)(h+\xi)^{\prime}\right) \\
& =E\left(\frac{\operatorname{tr}\left(G W G_{2}^{\prime} V\right)}{(h+\xi)^{\prime} B(h+\xi)}\right)-2 E \operatorname{tr}\left(\frac{G W G_{2}^{\prime} V}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}} B(h+\xi)(h+\xi)^{\prime}\right)
\end{aligned}
$$

Since

$$
G W G_{2}^{\prime} V=W G_{2}^{\prime} V G=W\left(V_{2}-V_{21}\right)
$$

and

$$
G W G_{2}^{\prime} V B=G W G_{2}^{\prime} V G\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-1} G^{\prime}=G W\left(V_{2}-V_{21}\right)\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-1} G^{\prime}
$$

set $W\left(V_{2}-V_{21}\right)\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-1}=C$, then

$$
E \operatorname{tr}\left(\frac{G W G_{2}^{\prime} V}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}} B(h+\xi)(h+\xi)^{\prime}\right)=E \operatorname{tr}\left(\frac{(h+\xi)^{\prime} G C G^{\prime}(h+\xi)}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}}\right)
$$

Thus

$$
\begin{align*}
E\left(\Psi^{* \prime} W \Psi^{*}\right)= & R\left(\hat{\beta}_{C C E P}\right)+\tau^{2} E\left(\frac{(h+\xi)^{\prime} G W G^{\prime}(h+\xi)}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}}\right)+4 \tau E \operatorname{tr}\left(\frac{(h+\xi)^{\prime} G C G^{\prime}(h+\xi)}{\left((h+\xi)^{\prime} B(h+\xi)\right)^{2}}\right) \\
& -2 \tau E \operatorname{tr}\left(\frac{\left(W\left(V_{2}-V_{21}\right)\right)}{(h+\xi)^{\prime} B(h+\xi)}\right) \tag{51}
\end{align*}
$$

Define $B_{1}=\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-\frac{1}{2}} G^{\prime}$ and $A=\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}} C\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}}$
Note that $G W G_{2}^{\prime} V B=G C G^{\prime}=B_{1}^{\prime} A B_{1}, B_{1}^{\prime} B_{1}=B$. Using the inequality $b^{\prime} a b \leq\left(b^{\prime} b\right) \lambda_{\max }(a)$ for symmetric $a$, and let

$$
\lambda_{\max }(a)=\lambda_{\max }\left(\frac{A+A^{\prime}}{2}\right)=\lambda_{1}
$$

Then

$$
\begin{align*}
\operatorname{tr}\left(B(h+\xi)(h+\xi)^{\prime} G W G_{2}^{\prime} V\right) & =\frac{(h+\xi)^{\prime} B_{1}^{\prime}\left(A+A^{\prime}\right) B_{1}(h+\xi)}{2} \\
& \leq(h+\xi)^{\prime} B(h+\xi) \lambda_{1} \tag{52}
\end{align*}
$$

Define $A^{*}=\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}} W\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{\frac{1}{2}}$. Note that $G W G^{\prime}=B_{1}^{\prime} A^{*} B_{1}, B_{1}^{\prime} B_{1}=B$, and let

$$
\lambda_{\max }(a)=\lambda_{\max }\left(\frac{A^{*}+A^{* \prime}}{2}\right)=\lambda_{1}^{*}
$$

we have

$$
\begin{align*}
\operatorname{tr}\left((h+\xi)^{\prime} G W G^{\prime}(h+\xi)\right) & =\frac{(h+\xi)^{\prime} B_{1}^{\prime}\left(A^{*}+A^{* \prime}\right) B_{1}(h+\xi)}{2} \\
& \leq(h+\xi)^{\prime} B(h+\xi) \lambda_{1}^{*} \tag{53}
\end{align*}
$$

Plug (52) and (53) into (51) and use Jensen's inequality, then we have

$$
\begin{align*}
E\left(\Psi^{* \prime} W \Psi^{*}\right) \leq & R\left(\hat{\beta}_{C C E P}\right)+\tau^{2} E\left(\frac{\lambda_{1}^{*}}{(h+\xi)^{\prime} B(h+\xi)}\right)+4 \tau E\left(\frac{\lambda_{1}}{(h+\xi)^{\prime} B(h+\xi)}\right) \\
& -2 \tau E \operatorname{tr}\left(\frac{\left(W\left(V_{2}-V_{12}\right)\right)}{(h+\xi)^{\prime} B(h+\xi)}\right) \\
= & R\left(\hat{\beta}_{C C E P}\right)-E\left(\frac{\tau\left(2\left(\operatorname{tr} W\left(V_{2}-V_{21}\right)-2 \lambda_{1}\right)-\lambda_{1}^{*} \tau\right)}{(h+\xi)^{\prime} B(h+\xi)}\right) \\
\leq & R\left(\hat{\beta}_{C C E P}\right)-\frac{\tau\left(2\left(\operatorname{tr} W\left(V_{2}-V_{21}\right)-2 \lambda_{1}\right)-\lambda_{1}^{*} \tau\right)}{E\left((h+\xi)^{\prime} B(h+\xi)\right)} \tag{54}
\end{align*}
$$

Since $\operatorname{tr}(B V)=\operatorname{tr}\left(G\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-1} G^{\prime} V\right)=q$. We have

$$
\begin{aligned}
E\left((h+\xi)^{\prime} B(h+\xi)\right) & =h^{\prime} B h+\operatorname{tr}(B V) \\
& =\sigma_{1}^{-4} \delta^{\prime} \Sigma^{\prime} V_{1}\left(V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right)^{-1} V_{1} \Sigma \delta+q
\end{aligned}
$$

Substitute into (54), then we have

$$
R\left(\hat{\beta}_{c}\right) \leq R\left(\hat{\beta}_{C C E P}\right)-\frac{\tau\left(2 \lambda_{1}(d-2)-\lambda_{1}^{*} \tau\right)}{\sigma^{-4} \delta \Sigma^{\prime} V_{1}\left[V_{1}+V_{2}-\left(V_{21}+V_{21}^{\prime}\right)\right]^{-1} V_{1} \Sigma \delta+q}
$$

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(a) $n=50, T=8, q=3, r=1$

(b) $n=100, T=8, q=3, r=1$

Figure 1: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=8, q=3$, $r=1$

(a) $n=50, T=8, q=3, r=3$

(b) $n=100, T=8, q=3, r=3$

Figure 2: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=8, q=3$, $r=3$

(a) $n=50, T=8, q=1, r=1$

(b) $n=100, T=8, q=1, r=1$

Figure 3: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=8, q=1$, $r=1$

(a) $n=50, T=8, q=2, r=1$

(b) $n=100, T=8, q=2, r=1$

Figure 4: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=8, q=2$, $r=1$

(a) $n=50, T=16, q=3, r=1$

(b) $n=100, T=16, q=3, r=1$

Figure 5: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=16, q=3$, $r=1$

(a) $n=50, T=16, q=3, r=3$

(b) $n=100, T=16, q=3, r=3$

Figure 6: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=16, q=3$, $r=3$

(a) $n=50, T=16, q=1, r=1$

(b) $n=100, T=16, q=1, r=1$

Figure 7: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=16, q=1$, $r=1$

(a) $n=50, T=16, q=2, r=1$

(b) $n=100, T=16, q=2, r=1$

Figure 8: Relative MSE of CCEP, FE, Pre-test and Combined Estimators, $n=\{50,100\}, T=16, q=2$, $r=1$

(a) $n=100, T=8, q=3, r=1, \beta=0$

(b) $n=100, T=8, q=3, r=1, \beta=1$

Figure 9: Relative MSE of CCEP, FE and Combined Estimators, $n=100, T=8, q=3, r=1, \beta=\{0,1\}$

(a) $n=100, T=8, q=3, r=3, \beta=0$

(b) $n=100, T=8, q=3, r=3, \beta=1$

Figure 10: Relative MSE of CCEP, FE and Combined Estimators, $n=100, T=8, q=3, r=3, \beta=\{0,1\}$

(a) $n=100, T=8, q=3, r=1, \tau$

(b) $n=100, T=8, q=3, r=1,2 \tau$

Figure 11: Relative MSE of CCEP, FE and Combined Estimators, $n=100, T=8, q=3, r=1,\{\tau, 2 \tau\}$

(a) $n=100, T=8, q=3, r=3, \tau$

(b) $n=100, T=8, q=3, r=3,2 \tau$

Figure 12: Relative MSE of CCEP, FE and Combined Estimators, $n=100, T=8, q=3, r=3,\{\tau, 2 \tau\}$

Table 1. Economics of Real House Prices: Correlated Common Effects

|  | $\hat{\beta}_{1}$ | $\hat{\beta}_{2}$ | $\hat{\beta}_{3}$ |
| :---: | :---: | :---: | :--- |
| FE | 0.5804 | 1.3286 | -0.5088 |
|  | $(0.3013)$ | $(1.8132)$ | $(0.1546)$ |
| CCEP | 1.2705 | 1.6367 | -0.1781 |
|  | $(0.2990)$ | $(1.5217)$ | $(0.1541)$ |
| Combined | 1.2151 | 1.6120 | -0.2047 |
|  | $(0.2986)$ | $(1.4237)$ | $(0.1530)$ |

Notes: 49 U.S. States. 1975-2011. Reported are parameter estimates with the standard errors in parentheses.


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